

$$\phi(t) = \{z \in E_+ : z >_t x(t)\} \cup \{e(t)\}. \quad (4.1)$$

We claim that:

$$\text{cl} \left(\int_T \phi - \int_T e \right) \cap \text{int } E_- = \emptyset, \quad (4.2)$$

or equivalently,⁵

$$\left(\int_T \phi - \int_T e \right) \cap \text{int } E_- = \emptyset. \quad (4.3)$$

Suppose otherwise, i.e.,

$$\left(\int_T \phi - \int_T e \right) \cap \text{int } E_- \neq \emptyset,$$

then there exists $v \in \text{int } E_+$ such that

$$\int e - v \in \int \phi. \quad (4.4)$$

It follows from (4.4) that there exists a function $y: T \rightarrow E_+$ such that

$$\int_T y = \int_T e - v, \quad (4.5)$$

and $y(t) \in \phi(t)$ μ -a.e.

Let

$$S = \{t: y(t) >_t x(t)\}, \quad \text{and}$$

$$S' = \{t: y(t) = e(t)\}.$$

Since $\int y \neq \int e$ we have that $\mu(S) > 0$. Define $\tilde{y}: S \rightarrow E_+$ by $\tilde{y}(t) = y(t) + v/\mu(S)$ for all $t \in S$. By monotonicity (assumption A.8) $\tilde{y}(t) >_t y(t)$. Since $y(t) >_t x(t)$ for all $t \in S$, by transitivity (assumption A.6) $\tilde{y}(t) >_t x(t)$ for all $t \in S$. Moreover, it can be easily seen that $\tilde{y}(\cdot)$ is feasible for the coalition S , i.e.,

⁵This is so since $\text{int } E_-$ is an open set. In particular, if A and B are subsets of any topological space and B is open, then it can be easily seen that $A \cap B = \emptyset$ if and only if $\text{cl } A \cap B = \emptyset$.