

the threshold on Pg used to stop merging is trained. This variant, too, performs less well than IS CRA.

Method	Covering		VOI		PRI	
	OIS	ODS	OIS	ODS	OIS	ODS
UCM[2]	0.65	0.59 ²³	1.54	1.66 ¹⁰	0.85	0.81 ⁵⁰
Hoiem[11]	0.59	0.55 ¹⁷	1.70	1.83 ¹⁰	0.82	0.79 ¹⁷
IS CRA	0.66	0.60 ¹²	1.40	1.61 ⁸	0.86	0.81 ¹⁶

Table 1. Results for large segment regime, **BSDS300**. OIS: optimal scale per (test) image, ODS: optimal scale for entire test data set. Superscripts: the average number of segments at the optimal scale for each method/measure. Best results are shown in bold.

Method	Covering		VOI		PRI	
	OIS	ODS	OIS	ODS	OIS	ODS
UCM[2]	0.64	0.59 ¹⁸	1.49	1.69 ¹³	0.85	0.83 ⁵⁹
Hoiem[11]	0.60	0.56 ¹⁸	1.66	1.78 ¹¹	0.84	0.81 ¹⁸
IS CRA	0.66	0.59 ²⁴	1.42	1.60 ¹⁰	0.85	0.82 ²⁴

Table 2. Large segment regime, **BSDS500**. See caption of Table 1.

Method	Covering		VOI		PRI	
	OIS	ODS	OIS	ODS	OIS	ODS
UCM[2]	0.74	0.64 ⁶	1.05	1.30 ³	0.85	0.78 ¹²
Hoiem[11]	0.67	0.65 ⁷	1.34	1.37 ⁷	0.80	0.77 ⁸
IS CRA	0.75	0.67 ⁴	1.02	1.18 ³	0.85	0.77 ¹⁴

Table 3. Large segment regime, **MSRC**. See caption of Table 1.

Method	Covering		VOI		PRI	
	OIS	ODS	OIS	ODS	OIS	ODS
UCM[2]	0.58	0.55 ⁷	1.70	1.75 ⁷	0.63	0.60 ⁷
Hoiem[11]	0.56	0.54 ⁷	1.72	1.73 ⁷	0.61	0.59 ⁷
IS CRA	0.57	0.56 ⁵	1.64	1.65 ⁵	0.62	0.60 ⁵

Table 4. Large segment regime, **VOC2012**. See caption of Table 1.

Method	Covering		VOI		PRI	
	OIS	ODS	OIS	ODS	OIS	ODS
UCM[2]	0.64	0.58 ²⁴	1.63	1.88 ¹¹	0.89	0.86 ⁴¹
[11]	0.67	0.62 ²⁰	1.52	1.64 ¹²	0.90	0.87 ²⁰
IS CRA	0.68	0.62 ²¹	1.50	1.73 ¹⁵	0.90	0.87 ³⁶

Table 5. Large segment regime, **SBD**. See caption of Table 1.

Method	Covering		VOI		PRI	
	OIS	ODS	OIS	ODS	OIS	ODS
UCM[2]	0.51	0.46 ¹⁴¹	2.33	2.52 ³⁴	0.90	0.88 ³³⁰
Hoiem[11]	0.51	0.48 ⁸⁷	2.36	2.50 ²⁸	0.89	0.88 ¹⁹⁴
IS CRA	0.54	0.50 ⁶²	2.21	2.34 ²⁰	0.90	0.89 ⁹⁷

Table 6. Large segment regime, **NYU**. See caption of Table 1.

6. Conclusions

We present IS CRA: Image Segmentation by Cascaded Region Agglomeration. IS CRA consists of a cascade of probabilistic models that predict the probability of grouping neighboring regions. It is trained in sequence, allowing adaptation of feature weights to increasing segmentation scale; when applied on an image it produces a hierarchical

segmentation, allowing the user to directly control the scale and the number of resulting regions. In experimental comparison on six data sets, IS CRA is a clear winner in region-based measures. It also is competitive in boundary-based measures in the superpixel regime, obtaining best results for part of the range for some data sets. IS CRA tends to achieve these results with fewer segments per image than other methods, making it potentially appealing for use as preprocessing step for semantic segmentation and other high-level perception tasks.

As the experiments show, a major limitation on IS CRA is its dependence on the initial segmentation. For instance, in our experiments here, it can not obtain ASA or boundary recall values above those of the finest scale of OWT-UCM. We plan to investigate initialization methods that combine fine-scale segmentations from multiple algorithms. We also are working on designing additional features that will improve accuracy of Pg estimated in later stages of IS CRA.

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